Periodic Quadratic Spline Interpolation*

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1. Introduction

Let $\Delta = \{x_i\}_{i=0}^N$ be a partition of [a,b], $a = x_0 < \cdots < x_N = b$. The length of the interval $[x_i, x_{i+1}]$ is $h_i = x_{i+1} - x_i$ ($i = 0, \dots, N - 1$), the mesh size of the partition is $\|\Delta\| = \max_i h_i$ and the mesh ratio of the partition is $\gamma(\Delta) = \|\Delta\|/\min_i h_i$. A partition Δ is uniform if its mesh ratio $\gamma(\Delta) = 1$. A family of partitions is regular if there exists a strictly positive constant γ such that $\gamma(\Delta) \geqslant \gamma$ for each partition Δ in the family.

A quadratic spline s is a function $s \in C^1[a, b]$ such that s restricted to $|x_i, x_{i+1}|$ is a polynomial of degree ≤ 2 . It is a periodic quadratic spline if $s^{(1)}(a) = s^{(1)}(b)$ (the condition s(a) = s(b) is not used here).

Throughout this paper we will use the following notations. If $g: [a, b] \to R$ is a given function, we will write $g_i = g(x_i)$, $x_{i+1/2} = (x_i + x_{i+1})/2$ and $g_{i+1/2} = g(x_{i+1/2})$. For a positive integer N we will note Z_N the set $\{0, 1, ..., N-1\}$ and Z_N^e (resp. Z_N^0) the set of even (resp. odd) numbers in Z_N .

In this paper we define a periodic quadratic spline from its nodal values $s_i(i=0,...,N)$. In Section 2, we recall an existence and uniqueness result and we give an explicit representation for the moments $s_i^{(1)}$ (i=0,...,N). In Section 3, if s is the periodic quadratic spline interpolant of $f \in C[a,b]$, we obtain error bounds of the form $||f^{(l)} - s^{(l)}||_{\infty} \simeq O(||\Delta||^{k+1-l})$ $(0 \le l \le k+1,0 \le k \le 2)$ which are valid only when the partition Δ is uniform.

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TABLE 1 Summary of the Convergence Results: $\|f - s\|_T \simeq O(\|A\|^m)$

m=1	$f \in C[a,b], f^{(1)} \in BV[a,b]$		Theorem 4
<i>m</i> = 2	(i) $f \in AC_p^{2, \epsilon}[a, b], f^{(2)} \in BV[a, b],$ (ii) $f \in AC_p^{3, 1}[a, b],$		Theorem 5 $(k-1)$ Theorem 7
m = 3	$f \in AC_p^{3,r}[a,b], f^{(3)} \in BV[a,b],$	uniform A	Theorem 5 $(k = 2)$

Table I gives a summary of our main results. In this table, and throughout this paper, we use the following notations:

$$AC^{k+1,q}[a,b] = \begin{cases} f \in C^k[a,b] & | (a)f^{(k+1)} \in L^q[a,b] \\ (b)f^{(k)}(s) = f^{(k)}(r) + \int_r^s f^{(k+1)}(\xi) d\xi, \forall r, s \in [a,b] \end{cases}$$

where $1 \le q \le \infty$ and $k \ge 0$, and

$$BV[a,b] = \{f: [a,b] \rightarrow R \mid Var(f) < \infty\},\$$

where Var(f) is the total variation of f on |a, b|. Moreover,

$$f \in AC_p^{k+1,q}[a,b]$$
 if $f \in AC^{k+1,q}[a,b]$ and $f^{(1)}(a) = f^{(1)}(b)$.

These results are extensions, to the periodic case, of those obtained by J. W. Daniel |2| and C. de Boor |1|. Finally, other quadratic spline interpolation approaches have been proposed before, for instance, see Kammerer et al. |5|, M. J. Marsden |7|, S. Demko |3|, E. Neuman |9| and Sharma and Tzimbalario |10|.

2. Existence of Periodic Quadratic Splines

As previously defined, on each interval $[x_i, x_{i+1}]$ a periodic quadratic spline can be written

$$s(x) = s_i + (x - x_i) s_i^{(1)} + \frac{(x - x_i)^2}{2h_i} (s_{i+1}^{(1)} - s_i^{(1)}).$$

Consequently

$$s_i^{(1)} + s_{i+1}^{(1)} = 2 \frac{s_{i+1} - s_i}{h_i}$$
 $(i = 0, ..., N-1),$ (1)

and this leads us to the following result (see also Meinardus and Taylor [8] and Krinzesza [6]).

THEOREM 1. Let $\Delta = \{x_i\}_{i=0}^N$ be a partition of [a,b]. A periodic quadratic spline is uniquely determined by its nodal values $\{s_i\}_{i=0}^N$ if and only if N is odd. In this case

$$\begin{bmatrix} s_0^{(1)} \\ s_1^{(1)} \\ s_2^{(1)} \\ \vdots \\ s_{N-1}^{(1)} \end{bmatrix} = \begin{bmatrix} 1 & -1 & 1 & \cdots & -1 & 1 \\ 1 & 1 & -1 & \cdots & 1 & -1 \\ -1 & 1 & 1 & \cdots & -1 & 1 \\ \vdots & \vdots & \vdots & \cdots & \vdots & \vdots \\ -1 & 1 & -1 & \cdots & 1 & 1 \end{bmatrix} \begin{bmatrix} (s_1 - s_0)/h_0 \\ (s_2 - s_1)/h_1 \\ (s_3 - s_2)/h_2 \\ \vdots \\ (s_N - s_{N-1})/h_{N-1} \end{bmatrix}. \tag{2}$$

If N is even, the spline does not exist or is not uniquely determined.

Proof. If we use the assumption of periodicity $s_0^{(1)} = s_N^{(1)}$, the matrix form of (1) is $As^{(1)} = b$, where

$$A = \begin{bmatrix} 1 & 1 & & & 0 \\ & 1 & 1 & & \\ & & \cdots & & \\ & 0 & & 1 & 1 \\ & & & & 1 \end{bmatrix}, \quad s^{(1)} = \begin{bmatrix} s_0^{(1)} \\ \vdots \\ s_{N-1}^{(1)} \end{bmatrix} \quad \text{and} \quad b = 2 \begin{bmatrix} (s_1 - s_0)/h_0 \\ \vdots \\ (s_N - s_{N-1})/h_{N-1} \end{bmatrix}.$$

Then det $A = 1 + (-1)^{N+1}$ and the result follows.

Q.E.D.

3. Derivation of Error Bounds

Given a function $f: [a, b] \to R$ and a partition $\Delta = \{x_i\}_{i=0}^N$, N odd, of the interval [a, b], we consider the periodic quadratic spline interpolant s of f such that $s(x_i) = f(x_i)$. By definition, the *remainder function* or *error* is e(x) = f(x) - s(x). In this section, we derive uniform bounds for the remainder function. Thus we extend the results of J. W. Daniel [2] and C. de Boor [1] to the periodic quadratic spline interpolation.

3.1. Preliminary Results

The study of the remainder function e rests on the behaviour of $e_i^{(1)}$ (i = 0,..., N).

PROPOSITION 2. Let k = 0, 1 or 2 and $f \in AC^{k+1,\infty}[a,b]$. If there exists a constant C_k and a real number α such that

$$\max\{|e_i^{(1)}|, |e_{i+1}^{(1)}|\} \leqslant C_k h_i^{\alpha} \tag{3}$$

for all $i \in Z_N$, then there exist constants C_{kl} which depend only on C_k and $||f^{(k+1)}||_{\infty}$, such that for almost all $x \in [x_i, x_{i+1}]$

$$|e^{(l)}(x)| \leq C_{kl}[h_i^{\alpha+1-l} + h_i^{k+1-l}]$$

for all l = 0,..., k+1 and $i \in Z_N$ (when k = 2 and l = 3 we rather have $||e^{(3)}||_{\alpha} = ||f^{(3)}||_{\alpha}$).

Proof. A direct adaptation of Stoer and Bulirsch's |11| Theorem 2.4.3.3 (see Dubeau and Savoie [4, Proposition 3.1]). Q.E.D.

We try now to obtain bounds of the form (3). A first step in this way is

PROPOSITION 3. Let k = 0, 1 or 2 and $f \in AC^{k+1}$, $[a, b] \cap C^1[a, b]$. Then there exists a constant C_k , independent of the partition, such that

$$|e_i^{(1)} + e_{i+1}^{(1)}| \leqslant C_k h_i^k ||f^{(k+1)}||, \tag{4}$$

for all $i \in Z_N$. Moreover, $C_0 = 4$, $C_1 = 1/2$ and $C_2 = 1/6$.

Proof. From (1) we always have

$$e_i^{(1)} + e_{i+1}^{(1)} = f_i^{(1)} + f_{i+1}^{(1)} - \frac{2}{h_i} \int_{x_i}^{x_{i+1}} f^{(1)}(\xi) d\xi$$

and $C_0 = 4$. If k = 1, through integration by parts, we obtain

$$e_i^{(1)} + e_{i+1}^{(1)} = \frac{2}{h_i} \int_{x_i}^{x_{i+1}} (\xi - x_{i+1/2}) f^{(2)}(\xi) d\xi$$

and $C_1 = 1/2$. If k = 2, through integration by parts agains, we obtain

$$e_i^{(1)} + e_{i+1}^{(1)} = \frac{h_i}{4} \int_{x_i}^{x_{i+1}} f^{(3)}(\xi) d\xi - \frac{1}{h_i} \int_{x_i}^{x_{i+1}} (\xi - x_{i+1/2})^2 f^{(3)}(\xi) d\xi$$
 (5)

and
$$C_2 = 1/6$$
. Q.E.D.

In view of (4), it remains to find good bounds for the quantities $|e_i^{(1)} - e_{i+1}^{(1)}|$ $(i \in Z_N^e)$, and we now consider this problem.

3.2. Uniform Convergence

THEOREM 4. Let $f \in C^1[a,b]$ and $f^{(1)} \in BV[a,b]$. (a) Then $|e_i^{(1)} - e_{i+1}^{(1)}| \le 2 \operatorname{Var}(f^{(1)})$ for all $i \in Z_N^e$. (b) Then there exist constants C_l , independent of the partition, such that

$$\|e^{(l)}\|_{\infty} \leqslant C_t \|\Delta\|^{1-l} [\|f^{(1)}\|_{\infty} + \operatorname{Var}(f^{(1)})]$$
 (6)

for l = 0 and 1.

Proof. If $f \in C^1[a, b]$, we deduce from (2)

$$e_1^{(1)} - e_0^{(1)} = |f_1^{(1)} - f_0^{(1)}| + 2\sum_{j=1}^{N-1} (-1)^j \frac{f_{j+1} - f_j}{h_j}.$$
 (7)

Similar expressions can be obtained for $e_{i+1}^{(1)} - e_i^{(1)}$ for all $i \in Z_N^e$, and for simplicity we consider only i = 0. But $f_{j+1} - f_j = h_j f^{(1)}(\tau_j)$, where $\tau_i \in (x_i, x_{j+1})$. Then (7) becomes

$$e_1^{(1)} - e_0^{(1)} = \left| f_1^{(1)} - f_0^{(1)} \right| + 2 \sum_{j \in \mathbb{Z}_0^0} \left\{ f^{(1)}(\tau_{j+1}) - f^{(1)}(\tau_j) \right\}$$

and the first part is proved. The second part follows from the first and Propositions 2 and 3.

Q.E.D.

The last theorem indicates that the remainder function is uniformly bounded and $||f - s||_{\infty} \to 0$ as $||\Delta|| \to 0$. The following example shows that we cannot improve (6) without any supplementary hypothesis.

EXAMPLE. Consider $f(x) = \sin \pi x$, $x \in [0, 1]$, and Δ a uniform partition of [0, 1]. The symmetry implies $s_0^{(1)} = 0 = s_N^{(1)}$. But $f^{(1)}(0) = \pi = -f^{(1)}(1)$, so $|e_0^{(1)}| = \pi = |e_N^{(1)}|$ and (6) cannot be imporved (see Table II note the effect on $||e||_{C}$).

The next example shows that the estimate (6) can fail if the hypothesis of Theorem 4 is not satisfied, furthermore, we can improve it with stronger hypothesis.

EXAMPLE. Consider $f(x) = (1+x)^{0.1} - (1-x)^{0.1}$, $x \in [-1+\varepsilon, 1-\varepsilon]$. When $\varepsilon = 0$, the hypothesis of Theorem 4 is not satisfied and we do not

TABLE II $f(x) = \sin \pi x. \ x \in [0, 1]$

N	$ A = \frac{1}{N}$	$ e ^*$, (a)	$\ e^{(1)}\ _{t}^{*-(a)}$
17	0.05882	0.4634 <i>E</i> -1	3.1594
35	0.03030	0.2382E-1	3.1463
65	0.01538	0.1209E-1	3.1428
129	0.00775	0.6089E-2	3.1419
257	0.00389	0.3056E-2	3.1417
513	0.00195	0.1531E-2	3.1416
1025	0.00098	0.7662E-3	3.1417

 $^{\|}e^{(t)}\|_{k}^*$ are estimations of $\|e^{(t)}\|_{k}$, and are computed according to $\|e^{(t)}\|_{k}^* = \max\{|e^{(t)}(y_{ij})\|y_{ij} = x_i + j\ (h_i/10), j = 0,..., 9, \text{ and } i \in Z_N\}.$

observe (6) (see Table III, K = 0, $\varepsilon = 0$). When $\varepsilon = 0.1$, we have $f \in C^{\infty} [-0.9, 0.9]$, $f^{(1)}(-0.9) = f^{(1)}(0.9)$ and we observe a great improvement of (6) (see Table III, K = 0, $\varepsilon = 0.1$).

3.3. The Uniform Case

In this section we consider only uniform partitions. Hence Theorem 4 can be extended in the following way.

THEOREM 5. Let k=1 or $2, f \in AC^{k+1,\infty}[a,b], f^{(k+1)} \in BV[a,b],$ and Δ a uniform partition of [a,b]. (a) Then there exists a constant C_k such that

$$|e_i^{(1)} - e_{i+1}^{(1)}| \le |f_N^{(1)} - f_0^{(1)}| + C_k ||\Delta||^k \operatorname{Var}(f^{(k+1)})$$

for all $i \in Z_N^e$ ($C_1 = 1/2$ and $C_2 = 1/6$). (b) Moreover, if $f \in AC_p^{k+1+\epsilon}$ [a, b], then there exist constants C_{kl} , independent of the partition, such that

$$||e^{(l)}||_{\alpha} \leqslant C_{kl} ||\Delta||^{k+1-l} \left[||f^{(k+1)}||_{\alpha} + \operatorname{Var}(f^{(k+1)}) \right]$$
(8)

for all l = 0, ..., k + 1.

Proof. When k = 1 or 2 and $f \in AC^{k+1,\infty}[a,b]$, we always have

$$f_{j+1} - f_j = \frac{h_j}{2} \left[f_{j+1}^{(1)} + f_j^{(1)} \right] - \left[\sum_{x_j}^{x_{j+1}} (\xi - x_{j+1/2}) f^{(2)}(\xi) d\xi,$$

so (7) becomes

$$e_1^{(1)} - e_0^{(1)} = \left[f_N^{(1)} - f_0^{(1)} \right] - 2 \sum_{i=1}^{N-1} \frac{(-1)^j}{h_i} \int_{x_i}^{x_{j+1}} (\xi - x_{j+1/2}) f^{(2)}(\xi) d\xi. \tag{9}$$

For a uniform partition Δ , the changes of variables $\eta = 2(\xi - x_{i+1/2})/h_i$ $(\xi \in [x_i, x_{i+1}], j \in Z_N)$ yield to

$$\begin{split} e_1^{(1)} - e_0^{(1)} &= \left| f_N^{(1)} - f_0^{(1)} \right| - \frac{\|\Delta\|}{2} \int_{-1}^{1} \eta \sum_{j \in \mathbb{Z}_N^0} \left[f^{(2)} \left(x_{j+3/2} + \eta \frac{\|\Delta\|}{2} \right) - f^{(2)} \left(x_{j+1/2} + \eta \frac{\|\Delta\|}{2} \right) \right] d\eta. \end{split}$$

The result follows for k = 1. When k = 2, through integration by parts, (9) becomes

$$e_1^{(1)} - e_0^{(1)} = \left| f_N^{(1)} - f_0^{(1)} \right| - \sum_{j=1}^{N-1} \frac{(-1)^j}{h_j} \int_{x_j}^{x_{j+1}} \left[\frac{h_j^2}{4} - (\xi - x_{j+1/2})^2 \right] f^{(3)}(\xi) d\xi$$
(10)

and, as before,

$$e_{1}^{(1)} - e_{0}^{(1)} = \left[f_{N}^{(1)} - f_{0}^{(1)} \right] - \frac{\|\Delta\|^{2}}{8} \int_{-1}^{1} (1 - \eta^{2}) \sum_{j \in \mathbb{Z}_{N}^{0}} \left[f^{(3)}(x_{j+3/2} + \eta \frac{\|\Delta\|}{2}) - f^{(3)}\left(x_{j+1/2} + \eta \frac{\|\Delta\|}{2}\right) \right] d\eta$$

$$(11)$$

and the proof of part (a) is completed. Part (b) is a direct consequence of (a) and Propositions 2 and 3.

Q.E.D.

The following examples show that the hypotheses of Theorem 5 are essential.

EXAMPLE. Consider $f(x) = (1+x)^{K+0.1} - (1-x)^{K+0.1}$, $x \in [-1+\varepsilon, 1-\varepsilon]$, and K=1 or 2. If $\varepsilon > 0$, then $f \in C_p^{\infty}[-1+\varepsilon, 1-\varepsilon]$ and we observe (12) in which k=2 (see Table III). If $\varepsilon = 0$ then $f \notin AC_p^{k+1,\infty}[-1,1]$ and the estimate (8) fails for k=K, but (8) is valid for k=K-1 since $f \in AC_p^{K,\infty}[-1,1]$ and $f^{(K)} \in BV[-1,1]$ (see Table III).

EXAMPLE. We will construct a function $f \in AC_p^{k+1,\infty}[0,1]$ such that $f^{(k+1)} \notin BV[0,1]$ and for which there exists a family of uniform partitions leading to $e_1^{(1)} - e_0^{(1)} \simeq O(\|\Delta\|^{k-1})$.

Consider k=2 (we essentially have the same situation when k=1). In fact, we construct simultaneously f and an increasing family $\{\Delta_n\}_{n=1}^{\infty}$ of uniform partitions. If $\{k_n\}_{n=1}^{\infty}$ is a strictly increasing sequence of positive integers where $k_1=0$, we define the partition $\Delta_n=\{i3^{-k_n}\mid i=0,...,3^{k_n}\}$. For each n=1,2..., let us define $f^{(3)}(x)$ for all $x\in (\|\Delta_{n+1}\|,\|\Delta_n\|]$ as follows:

$$f^{(3)}(x) = \frac{(-1)^{j-1}}{n} \text{ if } \begin{cases} x \in (j3^{-k_{n+1}}, (j+1)3^{-k_{n+1}}], \\ j = 1, \dots, 3^{k_{n+1}-k_n}. \end{cases}$$

It remains to choose $k_n(n \ge 2)$.

Assume $k_1,...,k_n$ fixed, hence $f^{(3)}$ is defined on the interval ($\|\Delta_n\|$, 1]. It is easy to show that $f^{(3)}$ is of bounded variation over ($\|\Delta_n\|$, 1], we will note this variation $\operatorname{Var}_n(f^{(3)})$. Now let us use (11) with the partition Δ_{n+1} . Then

$$e_1^{(1)} - e_0^{(1)} = \frac{\|\Delta_{n+1}\|^2}{8} \int_{-1}^{1} (1 - \eta^2) \times \left[\sum_{j=1}^{J-1} (-1)^{j+1} g_j(\eta) + \sum_{j=J}^{J-1} (-1)^{j+1} g_j(\eta) \right] d\eta,$$
 (12)

where

$$g_j(\eta) = f^{(3)}\left(x_{j+1/2} + \eta \cdot \frac{\|\Delta_{n+1}\|}{2}\right), J = 3^{k_{n+1}-k_n} \text{ and } \bar{J} = 3^{k_{n+1}}.$$

TABLE III $f(x) = (1+x)^{A+0.1} - (1+x)^{A+0.1}, x \in [-1+\epsilon, 1-\epsilon]$

K	ε	N	$\Delta \parallel = \frac{1}{N}$	$e^{(0)}$,	e ⁽¹⁾ ,	$(e^{(2)})_{i}$
0	0.1	 I 7	0.10588	0.8194 <i>E</i> -3	0.7281 <i>E</i> · 1	
		33	0.05455	0.1572E-3	0.2680E1	
		65	0.02769	0.2333E-4	0.8053E-2	
		129	0.01395	0.3065E-5	0.2158E-2	
		257	0.00700	0.3844E-6	0.5523E-3	
		513	0.00351	0.4777E-7	0.1392E-3	
		1025	0.00176	0.5941 <i>E</i> -8	0.3490E-4	
	0.0	17	0.11765	0.49455		
		33	0.06061	0.46281		
		65	0.03077	0.43248		
		129	0.01550	0.40383		
		257	0.00778	0.37693		
		513	0.00390	0.35176		
		1025	0.00195	0.32823		
1	0.1	17		0.6044E-4	0.5386E 2	
		33		0.9902E-5	0.1734E-2	
		65		0.1379E-5	0.4856E-3	
		129		0.1770E-6	0.1267E - 3	
		257		0.2215 <i>E</i> -7	0.3218E-4	
		513		0.2760E-8	0.8093E-5	
		1025		0.3444 <i>E</i> -9	0.2029 <i>E</i> 5	
	0.	17		0.1211 <i>E</i> -2	0.7217	
		33		0.5837E-3	0.6753	
		65		0.2769E-3	0.6311	
		129		0.1303E-3	0.5893	
		257		0.6104E-4	0.5500	
		513		0.2854E-4	0.5133	
		1025		0.1333E-4	0.4790	
2	0.1	17		0.1787E-4	0.1648E 2	0.8928E-1
		33		0.2583E-5	0.4687E-3	0.4951E-1
		65		0.3414E-6	$0.1241E \cdot 3$	0.2615E/1
		129		0.4343E-7	0.3178E-4	0.1344 <i>E</i> =1
		257		0.5455E-8	0.8025E - 5	0.6812 <i>E</i> = 2
		513		0.6826 <i>E</i> 9	0.2015E-5	0.3430 <i>E</i> -2
		1025		0.8482 <i>E</i> =10	0.5023 <i>E</i> 6	0.1718 <i>E</i> - 2
	0.	17		0.8300E-4	$0.799E \cdot 2$	1.7556
		33		0.2044E-4	0.3824E 2	1.6398
		65		0.4898E -5	0.1806E - 2	1.5307
		129		0.1158E 5	0.8477E-3	1.4285
		257		0.2719 <i>E</i> 6	0.3966E3	1.3329
		1025	A	0.1487 <i>E</i> -7	0.8650E-4	1.1604

From the definitions of $f^{(3)}$ and $Var_n(f^{(3)})$, (13) becomes

$$e_1^{(1)} - e_0^{(1)} \geqslant \frac{\|\Delta_{n+1}\|^2}{6} \left[\frac{1}{n} \left(\frac{\|\Delta_n\|}{\|\Delta_{n+1}\|} - 1 \right) - \operatorname{Var}_n(f^{(3)}) \right].$$

So if k_{n+1} is large enough, we deduce

$$e_1^{(1)} - e_0^{(1)} \geqslant ||\Delta_{n+1}||^{1+(2/n)}.$$

Since we can do that for all n=1, 2,..., we define $f^{(3)} \in L^{\infty}[0, 1]$. It is easy to show that $f^{(3)} \notin BV[0, 1]$, and if we integrate $f^{(3)}$ and add some appropriate constants of integration, we obtain our desired function $f \in AC_n^{3,\infty}[0, 1]$.

3.4. The Regular Case

When the partition is not uniform, we generally cannot establish (8) without a stronger hypothesis. However, without any assumption on the partition Δ we can deduce from Proposition 3 this local result.

THEOREM 6. Let k=1 or 2 and $f \in AC_p^{k+1,\infty}[a,b]$. Then there exists at least one index i that possibly depends on the partition Δ and the function f, such that

$$\begin{split} \max\{|e_i^{(1)}|,|e_{i+1}^{(1)}|\} &\leqslant C_k \, \|f^{(k+1)}\|_{\mathcal{L}} \, h_i^k, \\ \min\{|e_i^{(1)}|,|e_{i+1}^{(1)}|\} &\leqslant \frac{C_k}{2} \, \|f^{(k+1)}\|_{\mathcal{L}} \, h_i^k. \end{split}$$

where $C_k = 1/(k+1)$. Moreover, there exist constants C_{kl} independent of the partition Δ , such that for almost all $x \in [x_i, x_{i+1}]$

$$|e^{(l)}(x)| \leq C_{kl} h_i^{k+1-l}$$

for all l = 0,..., k + 1.

Proof. Consider $Z_N = Z_N^+ \cup Z_N^-$, where $Z_N^+ = \{i \in Z_N \mid e_i^{(1)} \ge 0\}$ and $Z_N^- = \{i \in Z_N \mid e_i^{(1)} < 0\}$. Since N is odd, there exist at least two successive indices, with respect to Z_N , in Z_N^+ or in Z_N^- . Then we deduce the first two inequalities from (4) and the periodicity of $e^{(1)}$. These inequalities and Proposition 2 complete the proof.

Q.E.D.

There exists a large class of functions for which (8), with k = 1, remains valid even for non-uniform partitions.

THEOREM 7. Let $f \in AC_p^{3,1}[a,b]$. (a) Then $\max\{|e_i^{(1)}|, |e_{i+1}^{(1)}|\} \le (||\Delta||/2)$ $||f^{(3)}||_1$ for all $i \in Z_N$. (b) There exist constants $C_l(\gamma)$, that depend on the mesh ratio γ , such that

$$|e^{(t)}|_{t} \le C_{t}(\gamma) ||f^{(3)}|_{1} ||A||^{2-\epsilon}$$

for all l = 0, 1 or 2.

Proof. Equations (5) and (10), respectively, to $|e_i^{(1)} + e_{i+1}^{(1)}| \le (h_i/2) ||f^{(3)}||_1$ and $|e_i^{(1)} - e_{i+1}^{(1)}| \le (||\Delta||/4) ||f^{(3)}||_1$ for all $i \in Z_N^c$. Hence (a) follows. To prove the second part, consider

$$e^{(2)}(x) = \frac{e_i^{(1)}}{h_i} - \frac{e_{i+1}^{(1)}}{h_i} - \frac{1}{h_i} \Big|_{YX}^{X_{i+1}} \Big|_{Y}^{\xi} f^{(3)}(\tau) d\tau d\xi.$$

Then $|e^{(2)}(x)| \le (\gamma + 1) \|f^{(3)}\|_1$. Since there exists $\xi \in (x_i, x_{i+1})$ such that $e^{(1)}(\xi) = 0$, we have $e^{(1)}(x) = \int_{t}^{x} e^{(2)}(t) dt$ and $|e^{(1)}(x)| \le h_i(\gamma + 1) \|f^{(3)}\|_1$ for all $x \in [x_i, x_{i+1}]$. Finally, since $e_i = 0$ (i = 0, ..., N), we obtain $|e(x)| \le ((\gamma + 1)/2) \|h_i^2\| \|f^{(3)}\|_1$. Q.E.D.

On the other hand, for the estimate (8) in which k = 2 the situation is quite different. Indeed, for a given smooth function it is easy to construct a regular family of partitions for which (8) fails.

EXAMPLE. Consider $f(x) = x^3/3!$, $x \in [-1, 1]$. Thus $f \in C_p^{(x)}[-1, 1]$, $f^{(3)}(x) = 1$ and (10) becomes

$$e_0^{(1)} - e_1^{(1)} = \frac{1}{6} \sum_{j \in \mathbb{Z}_2^0} (h_{j+1}^2 - h_j^2).$$

For an arbitrary but fixed β , $0 < \beta < 1$, let us define the $h_i (i \in Z_x)$ as

$$h_i = ||\Delta||$$
 if $i \in Z_N^c$,
= $\beta ||\Delta||$ if $i \in Z_N^0$,

so that $\|\Delta\| \|1 + (N-1)(1+\beta)/2\| = 2$. Then $e_0^{(1)} - e_1^{(1)} = (\|\Delta\|^2/6)(N-1)(1-\beta^2)/2$. But $\|\Delta\| (N-1)/2 \to 2/(1+\beta)$ as $N \to \infty$, ensuring that $e_0^{(1)} - e_1^{(1)} = O(\|\Delta\|)$. This, together with (4), shows that $e_0^{(1)} - e_1^{(1)}$ are only $O(\|\Delta\|)$. A numerical example appears in Table IV with $\beta = 0.2$.

The last result, deduced from the preceding example, shows that the class of functions for which the estimate (8), with k = 2, fails is rather large.

THEOREM 8. Let $f \in C_p^3[a,b]$, $f^{(3)} \in BV[a,b]$ and f is not a polynomial of degree ≤ 2 . Then there exists a constant C such that for all $\gamma > 1$ we can

V	<i>d</i> 1	$\ e^{in}\ _{+}^{*}$	$e^{i \oplus j} \mathbb{F}_{i}^{*}$	$e^{(2)}!^{*}$
17	0.18868	0.1075 <i>E</i> -2	0.2575 <i>E</i> -1	1.0755
33	0.09901	0.3106E-3	0.1336E-1	1.1980
65	0.05076	0.8371E-4	0.6811E-2	1.2640
129	0.02571	0.2175E-4	$0.3439E \cdot 2$	1.2982
257	0.01294	0.5542E-5	0.1728E - 2	1.3157
513	0.00649	0.1400E-5	0.8659E-3	1.3245
025	0.00325	0.351E-6	0.4335E-3	1.3289

TABLE IV $f(x) = x^3/3!, x \in [-1, 1]$

choose a non-uniform partition of arbitrarily small mesh size $\|\Delta\|$ and of mesh ratio γ for which

$$e_0^{(1)} - e_1^{(1)} \geqslant \left(1 - \frac{1}{\gamma}\right) C \|f^{(3)}\|_{\infty} \|\Delta\| - \frac{\|\Delta\|^2}{6} \operatorname{Var}(f^{(3)}).$$

Proof. From the hypothesis, we can find a non-empty interval $|c,d| \subset [a,b]$ such that for all $x \in [c,d]$, $f^{(3)}(x) \ge (\|f^{(3)}\|_{\infty}/2)$. Let us take N odd and $\|\Delta\| = (b-a)/[1+(1+\beta)(N-1)/2]$, where $0 < \beta = 1/\gamma < 1$. The knots of the partition Δ are then chosen as follows:

$$x_{0} = a, x_{1} = ||\Delta||,$$

$$x_{j} = x_{1} + \frac{j-1}{2} (1+\beta) ||\Delta||, j \in Z_{N}^{0},$$

$$x_{j+1} = x_{j} + \beta ||\Delta|| \text{if } |x_{j}, x_{j+2}| \subset [c, d],$$

$$= x_{j} + \frac{(1+\beta)}{2} ||\Delta|| \text{if } |x_{j}, x_{j+2}| \notin [c, d],$$

$$j \in Z_{N}^{0}.$$

If we note $\overline{Z}_N^0 = \{j \in Z_N^0 | |x_j, x_{j+2}| \subset [c, d]\}$ and use the change of variables $\eta = 2(\xi - x_{j+1/2})/h_j$ $(\xi \in [x_j, x_{j+1}], j \in Z_N)$, then (10) becomes, for the partition Δ defined below,

$$e_0^{(1)} - e_1^{(1)} = \frac{\|\Delta\|^2}{8} \int_{-1}^1 (1 - \eta^2) \sum_{j \in \overline{Z}_1^0} \left(f^{(3)} \left(x_{j+3/2} + \frac{\eta}{2} h_{j+1} \right) - f^{(3)} \left(x_{j+1/2} + \frac{\eta}{2} h_j \right) \right) d\eta$$

$$\begin{split} & + \frac{(1-\beta)\|\Delta\|}{8} \int_{-1}^{1} (1-\eta^{2}) \sum_{j \in \overline{Z}_{N}^{0}} (h_{j} + h_{j+1}) \\ & \times f^{(3)} \left(x_{j+1/2} + \frac{\eta}{2} h_{j} \right) d\eta \\ & + \frac{(1-\beta)^{2} \|\Delta\|^{2}}{32} \int_{-1}^{1} (1-\eta^{2}) \sum_{j \in \overline{Z}_{N}^{0}} \left(f^{(3)} \left(x_{j+3/2} + \frac{\eta}{2} h_{j+1} \right) - f^{(3)} \left(x_{j+1/2} + \frac{\eta}{2} h_{j} \right) \right) d\eta. \end{split}$$

hence

$$|e_0^{(1)} - e_1^{(1)}| \ge \frac{(1-\beta)\|\Delta\|}{12} \|f^{(3)}\|_{\infty} \sum_{i \in \overline{\mathbb{Z}}^0} (h_j + h_{j+1}) - \frac{\|\Delta\|^2}{6} \operatorname{Var}(f^{(3)}).$$

If $||\Delta||$ is small enough, we have $\sum_{j \in \overline{Z}_N^0} (h_j + h_{j+1}) \geqslant (d-c)/2$ and the result follows with C = (d-c)/24. Q.E.D.

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